

Rapid CAD and tetrahedral mesh generation for dynamic rupture problems





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SeisSol - Project overview



Coordination, Host, Physics, Numerics, Algorithm, Pre- and Postprocessing, Application, User support



Consulting, Scaling, BlueGene/Q adaption





Meshing, CAD generation



Technical development, HPC, Optimization, Visualization, Design



Visualization, parallel I/O









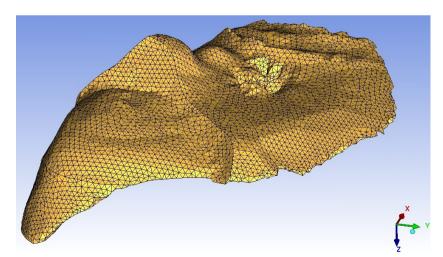
...and others ... Support, Guidance, Experience sharing, Consulting, ...

Goal

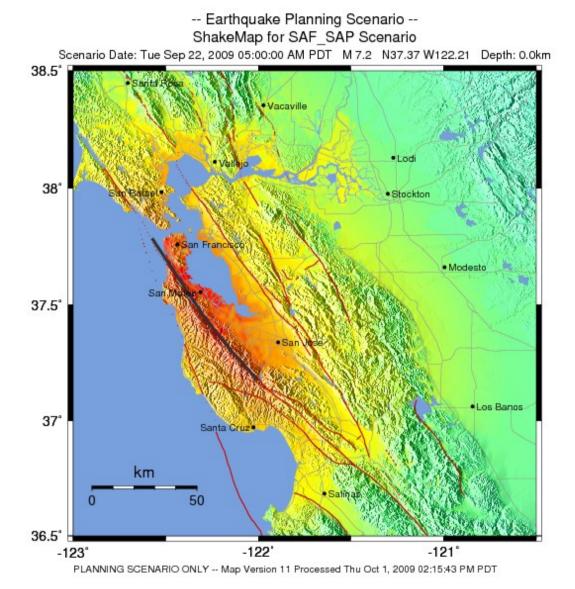
Complete seismic wave propagation package including solutions for

- dynamic rupture simulations
- exploration industry
- Seismology

with complex geometry and heterogeneous medium.



Käser, Martin, Christian Pelties, E. Cristobal Castro, Hugues Djikpesse, and Michael Prange (2010), **Wave Field Modeling in Exploration Seismology Using the Discontinuous Galerkin Finite Element Method on HPC-infrastructure**, *The Leading Edge*



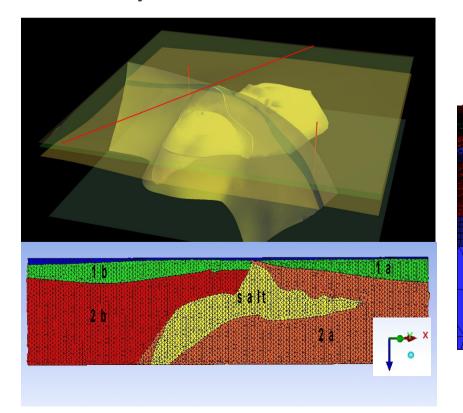
Warmer colors = higher intensity

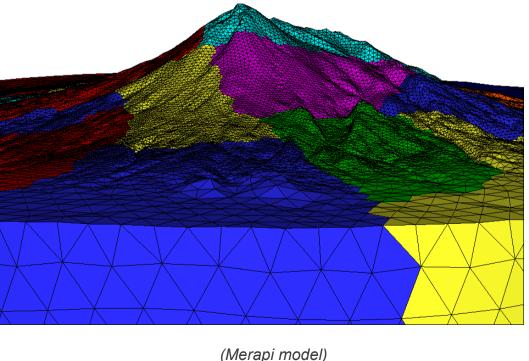
USGS - http://earthquake.usgs.gov/earthquakes/shakemap/ (modified)

Requirements for solver

What do we need for this?

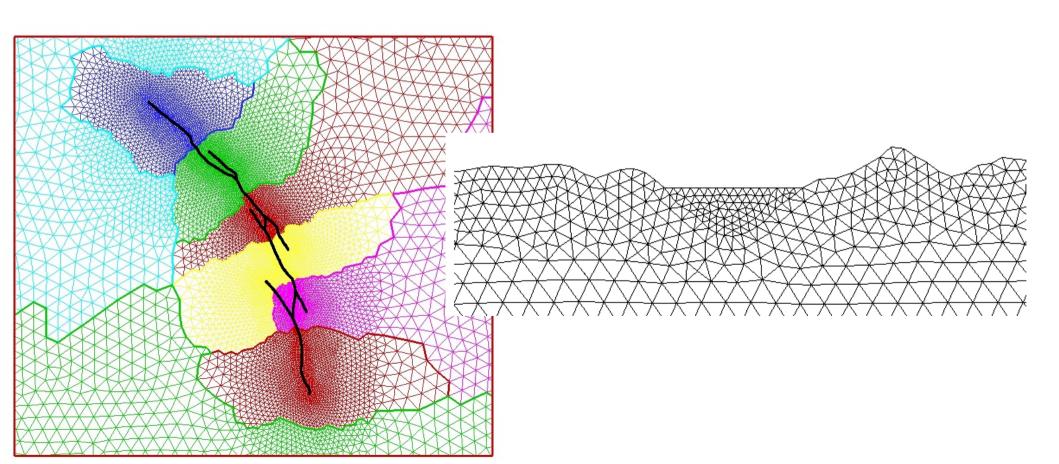
- Accurate numerical methods for reliable results (num. errors, boundary-, initial conditions)
- Proper geometry representation (topography, material interfaces)
- Use of acoustic, elastic, viscoelastic, and anisotropic material to approximate realistic geological subsurface properties
- Scalability on HPC architecture to tackle big problems with high frequency





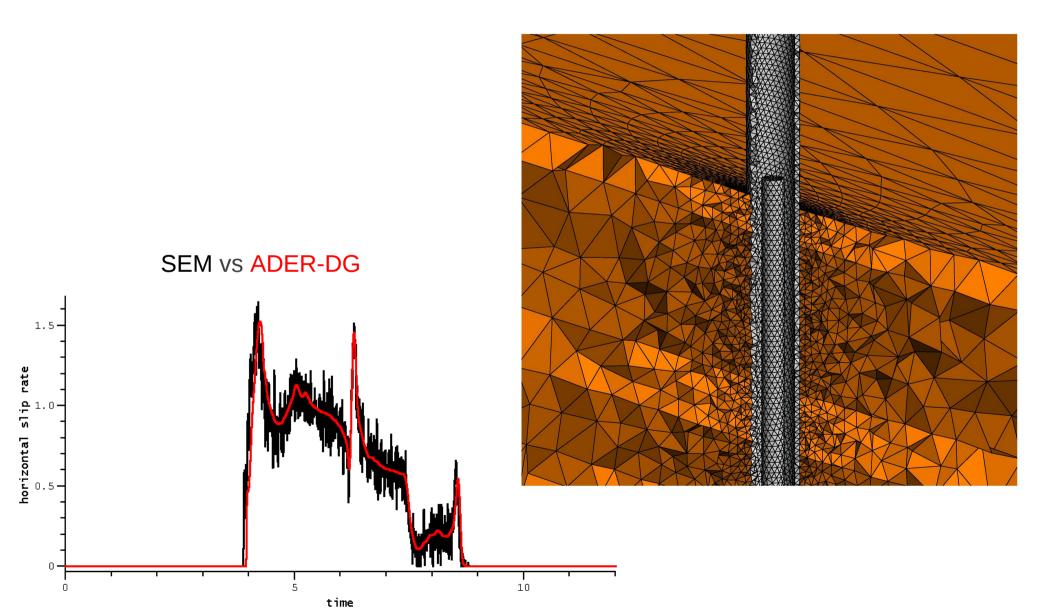
Advantages of the ADER-DG Method

- Enables use of unstructured meshes low velocity basins, curved or kinked faults, branching, surface rupture, fault interaction
- Mesh coarsening adjustment of resolution
- High-order accurate simulation of the wave propagation including heterogeneous media and topography



Advantages of the ADER-DG Method

- ADER high-order time integration with local time stepping
- High-accurate results of the rupture process: Oscillation free dynamic rupture



Mathematical Model

Elastic Wave Equation as a Linear Hyperbolic System:

Vector-matrix notation:

$$\frac{\partial Q_p}{\partial t} + A_{pq} \frac{\partial Q_q}{\partial x} + B_{pq} \frac{\partial Q_q}{\partial y} + C_{pq} \frac{\partial Q_q}{\partial z} = S_p$$

Velocity-stress formulation:

3D:
$$Q = (\sigma_{xx}, \sigma_{yy}, \sigma_{zz}, \sigma_{xy}, \sigma_{yz}, \sigma_{xz}, u, v, w)^T$$

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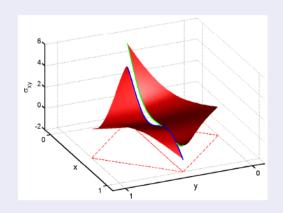
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Numerical Approximation of the solution

$$\left(Q_h^{(m)}\right)_p(\xi,\eta,\zeta,t) = \hat{Q}_{pl}^{(m)}(t)\Phi_l(\xi,\eta,\zeta)$$

- ullet Φ_l are orthogonal basis functions
- the mass matrix is diagonal



Discontinuous Galerkin Approach – Flux computation

Flux computation

Exact Riemann solver is used to compute the state at the interfaces by upwinding:

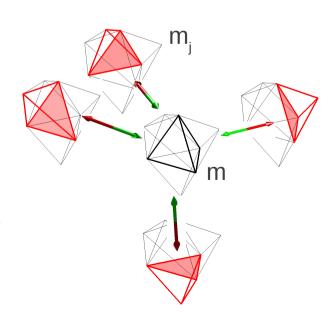
$$F_{p}^{h} = \frac{1}{2} T_{pq} \left(A_{qr}^{(m)} + \left| A_{qr}^{(m)} \right| \right) (T_{rs})^{-1} \hat{Q}_{sl}^{(m)} \Phi_{l}^{(m)}$$

$$+ \frac{1}{2} T_{pq} \left(A_{qr}^{(m)} - \left| A_{qr}^{(m)} \right| \right) (T_{rs})^{-1} \hat{Q}_{sl}^{(m_{j})} \Phi_{l}^{(m_{j})}$$

Computation of the line integrals:

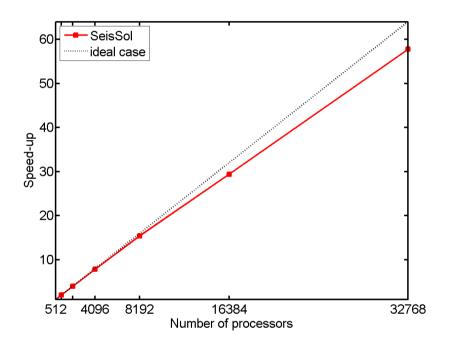
- Pre-computed analytically
- Gauss-Legendre integration
- Opens up new possibilities: non-conforming meshes, dynamic rupture source type

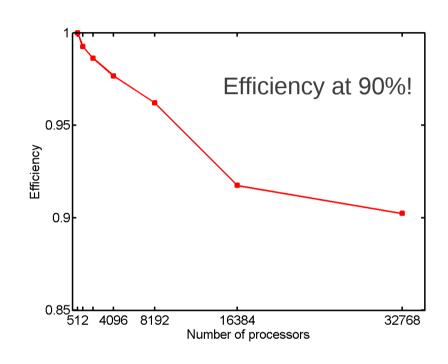
Locality of the computations: only directly neighboring elements are required to exchange data, which leads to small communication times for parallel calculations



Suitability for large scale HPC infrastructure

Efficiency on the BlueGene/P machine Shaheen at KAUST





- 7,7 Mio. Elements
- Order of accuracy in space and time: O5
- Pure MPI parallelization code is openMP hybrid now
- Metis partitioning http://glaros.dtc.umn.edu/gkhome/metis/metis/overview

Dynamic Earthquake rupture

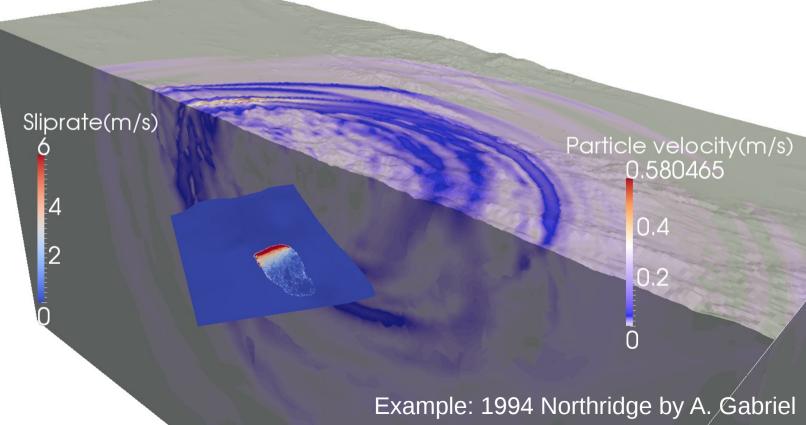
Incorporate source process

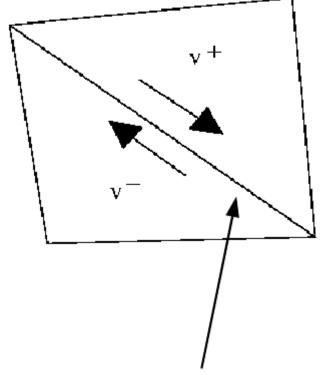
- To understand earthquake faulting
- Support physics-based ground motion prediction

Treat dynamic rupture as an interior time-dependent 'boundary condition' using the flux term!

Impose new traction following the failure criterion

• Impose fault parallel velocities in opposite directions



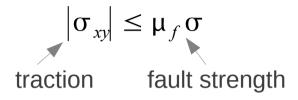


fault between two elements

Ingredients Initial Shear Traction τ_0 Distance Down Dip [km] [MPa] 80 60 10 40 20 Maps of the Southern California fault structure . Dots are earthquake centers. 15 10 15 20 25 30 40 35 45 (Shaw et al. for SCEC, 2003) Distance Along Strike [km] (Brietzke et al. (2009)) Geologic Structure (Fault Geometry & Material Properties) Initial friction: Failure **Fault Stresses** Criterion non linear relation between fault stress and slip **Computer Program** that Simulates Earthquakes as **Spontaneous Ruptures Ground Shaking** (Seismograms), (Harris et al. (2009)) Fault Slip, etc.

Failure criterion:

Coulomb friction model



$$(|\sigma_{xy}| - \mu_f \sigma) \Delta v = 0$$

 σ_{xy} traction

 μ_f friction coefficient

 σ normal stress

 Δv slip rate

Failure criterion:

Coulomb friction model

$$\left|\sigma_{xy}\right| \leq \mu_f \sigma$$
traction fault strength

$$(|\sigma_{xy}| - \mu_f \sigma) \Delta v = 0$$

 σ_{xy} traction

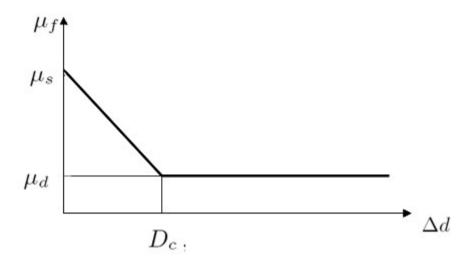
 μ_f friction coefficient

 σ normal stress

 Δv slip rate

 Δd slip

 D_c critical slip distance



Linear Slip Weakening friction law (laboratory experiments

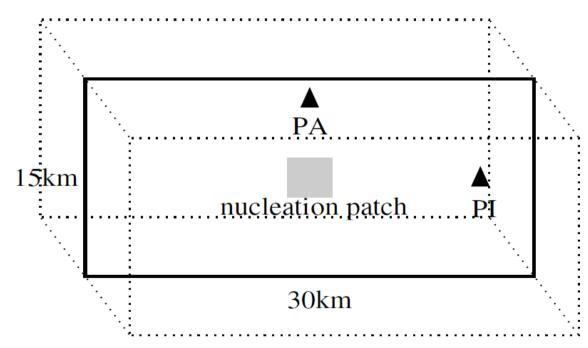
– rate-and-state also implemented)

Provides:

- initial rupture
- arrest of sliding
- reactivation of slip

(Harris et al., 2004)

- spontaneous rupture propagation on a straight fault
- homogeneous fullspace
- linear slip weakening friction

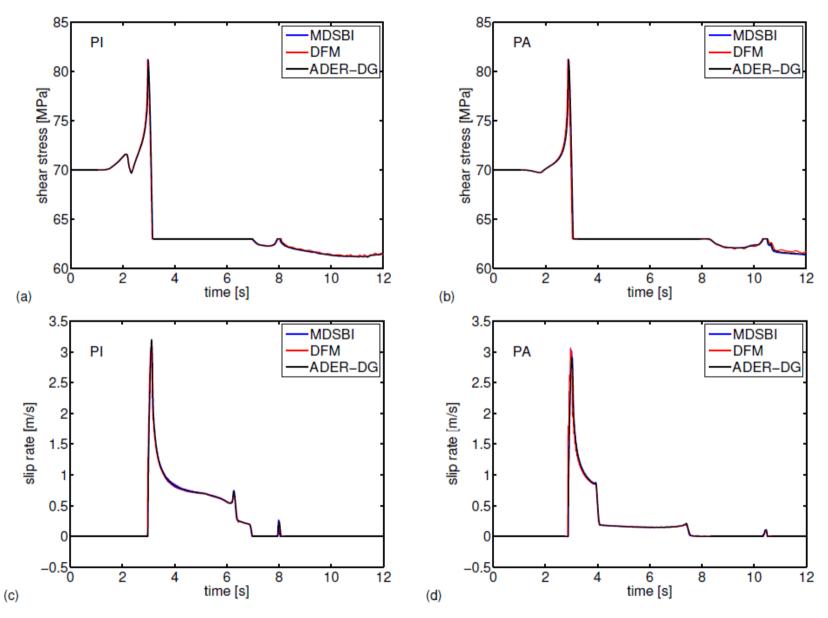


Comparison between

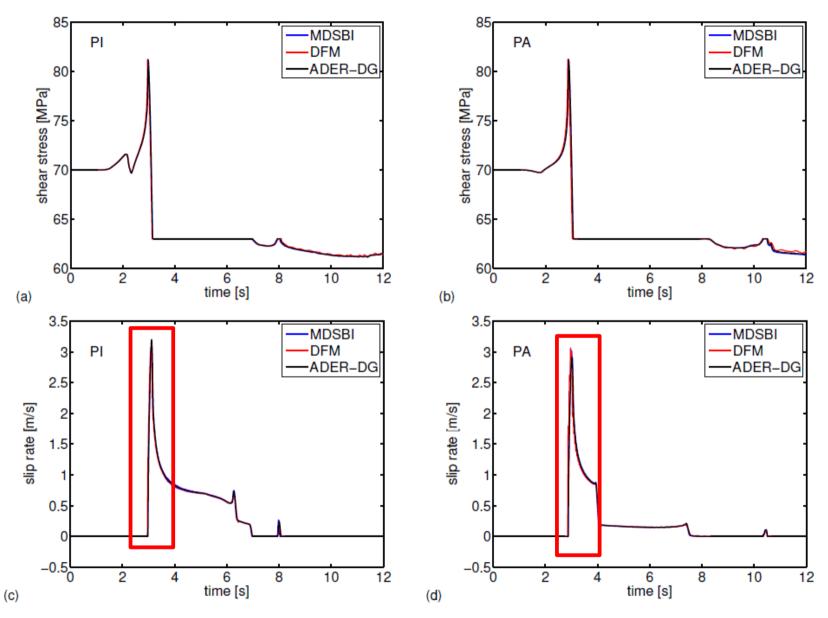
ADER-DG method <u>order 4</u> and <u>200m triangles</u> at the fault (larger tetrahedrons in bulk) and

DFM - Finite Difference staggered-grid split node order 2 with 50m grid interval and

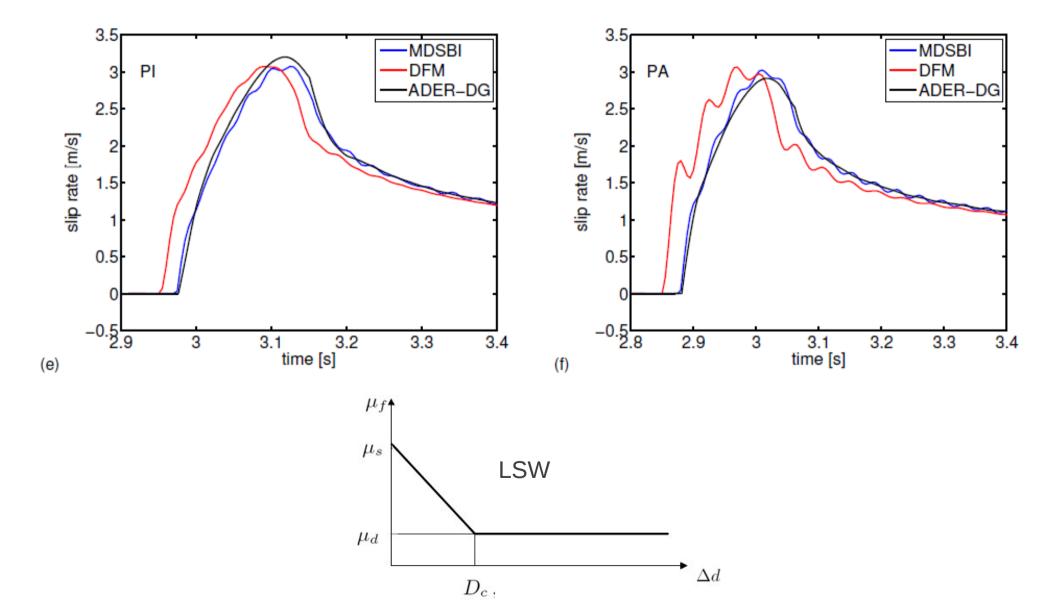
MDSBI - Multidimensional spectral boundary integral with 50m grid interval



Day, S. M., L. A. Dalguer, N. Lapusta, Y. Liu (2005), Comparison of finite difference and boundary integral solutions to three-dimensional spontaneous rupture, J. Geophys. Res., 110, B12307 DFM data provided by Luis Dalguer. MDSBI data computed with the code of E. Dunham (version 3.9.10).



Day, S. M., L. A. Dalguer, N. Lapusta, Y. Liu (2005), Comparison of finite difference and boundary integral solutions to three-dimensional spontaneous rupture, J. Geophys. Res., 110, B12307 DFM data provided by Luis Dalguer. MDSBI data computed with the code of E. Dunham (version 3.9.10).



Workflow

From CAD to seismogram...

- Get geometry and model data
- Assemble CAD model
- Create mesh
- Partitioning
- Set model parameters
- Solve physical equation
- Analysis of output



"Time to solution!"

Pre-processing

Post-processing

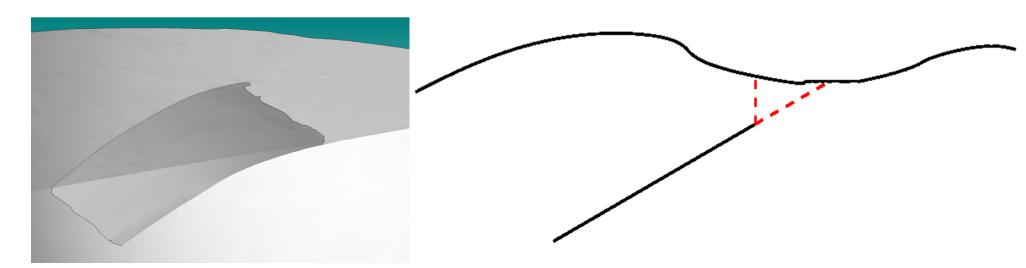


Automated CAD generation

Current bottleneck: CAD generation can easily consume weeks to month

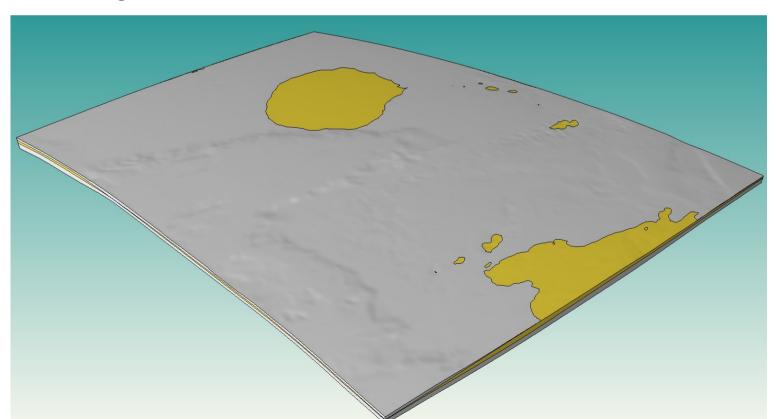
Difficulties:

- Surface reconstruction of different types of initial raw data
- Undulating 3D surfaces that merge under shallow angles, intersect
- Remove non-physical features
- Clip too small features depending on the desired mesh size
- Representation by splines as typically used by (commercial) CAD/mesh software unfortunate for geological data
- Watertight model
- Seamless integration into meshing software (avoid format conversion)



Automated CAD generation – preliminary workflow

- 1. Download topography/bathymetry, e.g. from NOAA's ETOPO data collection
- 2. Define bounding box: rectangular or spherical
- 3. Material interfaces: structured grids of points
- 4. Faults: structured grids of points, gOcad's TS format
- 5. Check projection
- 6. (Triangulated) surface generation: Poisson surface reconstruction (MeshLab)
- 7. Assemble model: apply union, intersection, trimming operations with Simmetrix discrete modeling tools

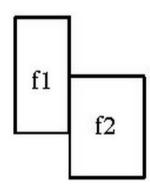


Biscay model, S. Wenk

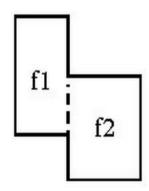
SimModeler

Customized problem definition and mesh generation interface for SeisSol by RPI/SCOREC/Simmetrix (C. Smith, M. Shephard)

- Accepts e.g. Parasolid, ACIS and STL input
- Trims automatically geometry and creates a watertight model
- Meshes with millions of elements in seconds/minutes
- Mesh coarsening/refining
- Handling complex geometries (no violation)
- user-friendly interface
- Quality metrics
- Exports SeisSol format
- Non-manifold geometry required

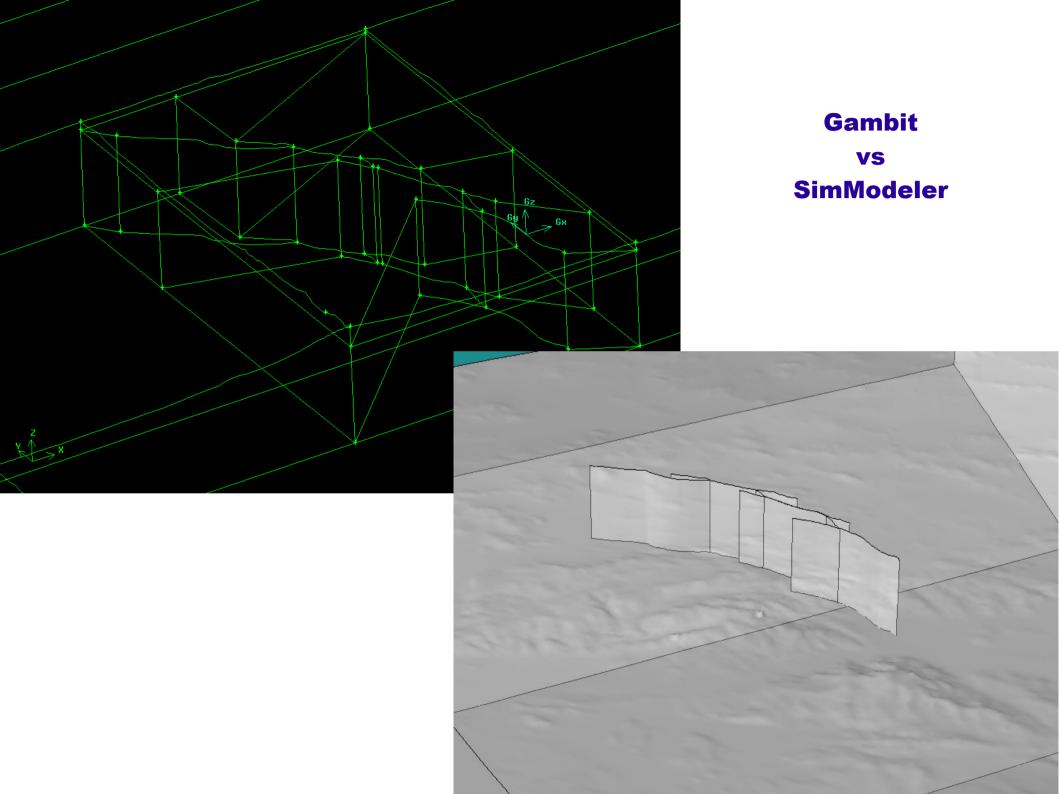


Two faces. At the intersection there are two edges overlapping. = assembly

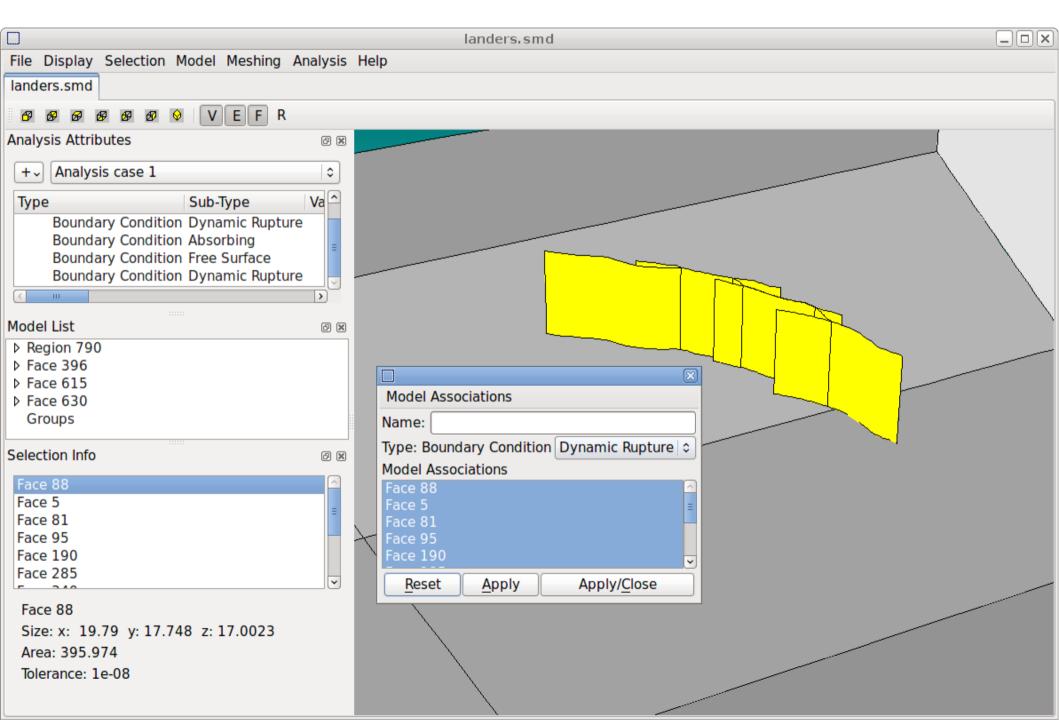


Two faces. At the intersection there is one shared edge.

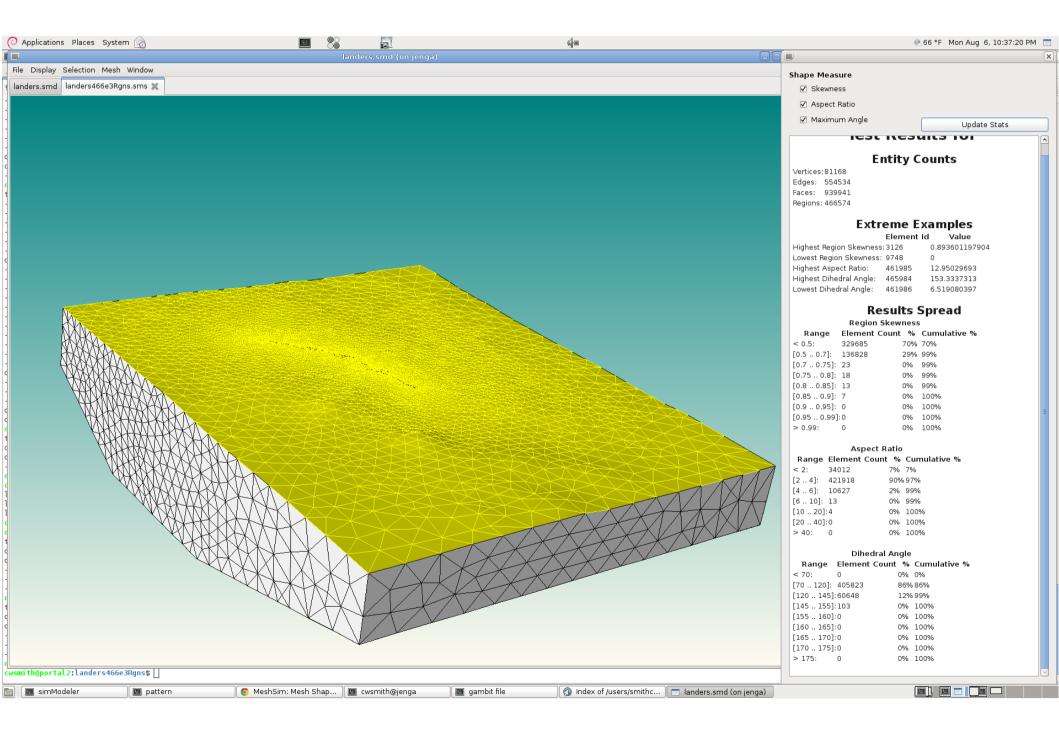
= non-manifold



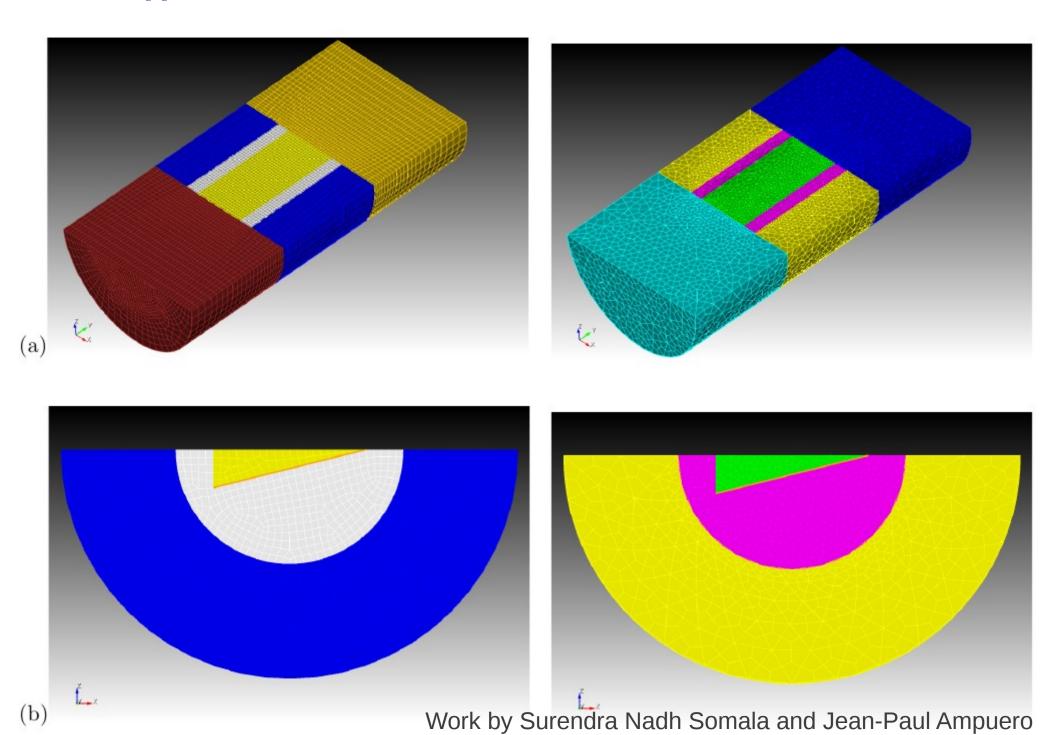
SimModeler



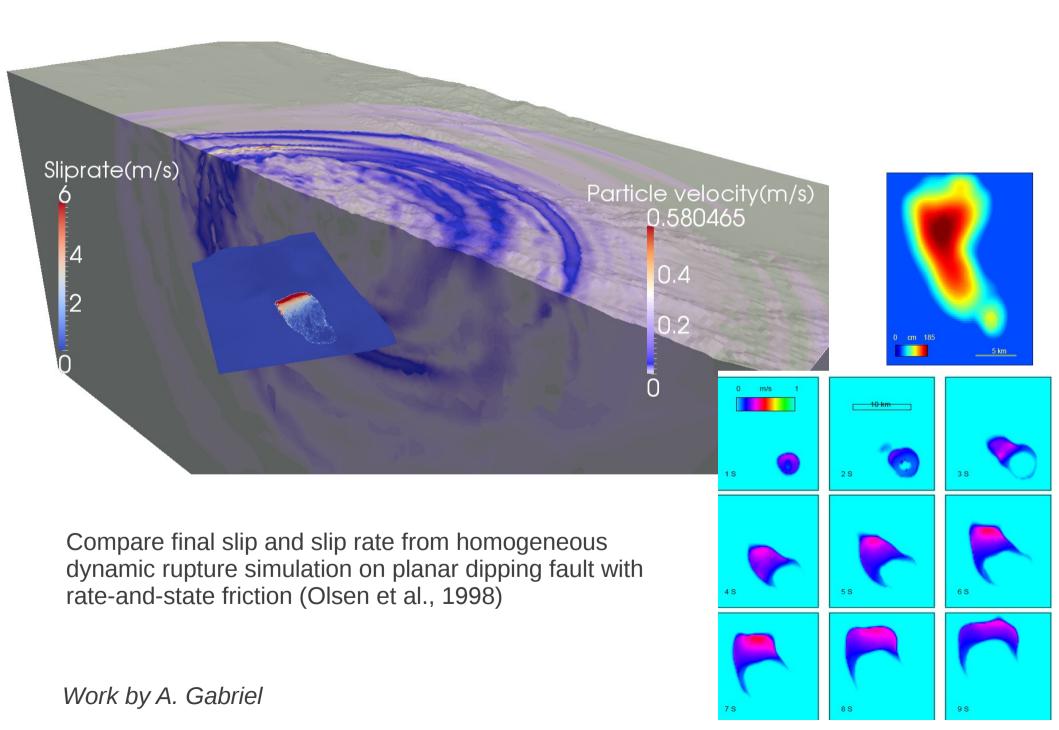
SimModeler



THex approach



Example – The Mw 6.7 1994 Northridge earthquake



Conclusion & Outlook

- ADER-DG solver ready, functional and benchmarked
- Bring all features into production version (under construction)
- Combine dynamic rupture with local time stepping

- Current bottleneck CAD generation (under construction)
- Use CAD for quality control

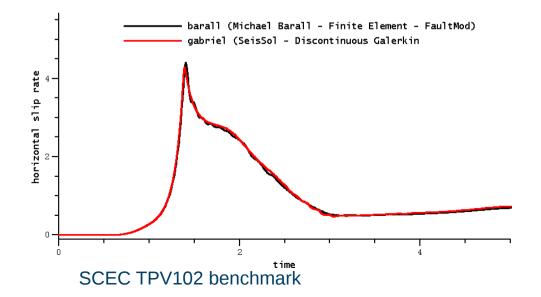
Open Source (soon), already available through http://verce.eu/

http://seissol.geophysik.uni-muenchen.de/

Failure criterion

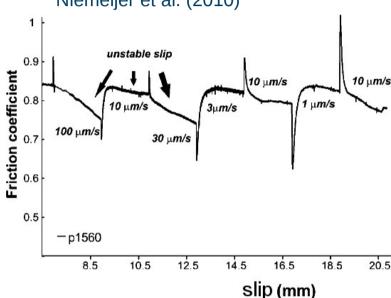
Implementation of rate-and-state friction

 Updating scheme includes Newton-Raphson search for slip rate and two iterations for state variable (Kaneko et al., 2008)



Rate-and-state dependent friction

Velocity-stepping experiment of Niemeijer et al. (2010)



$$\mu_f = \mu_0 + a \ln \frac{v}{v_0} + b \ln \frac{v_0 \theta}{D_c}$$

$$\dot{\theta} = 1 - \frac{v \theta}{D_c}$$

 θ state variable

a direct effect

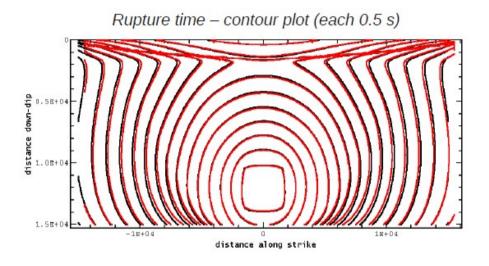
b evolution effect

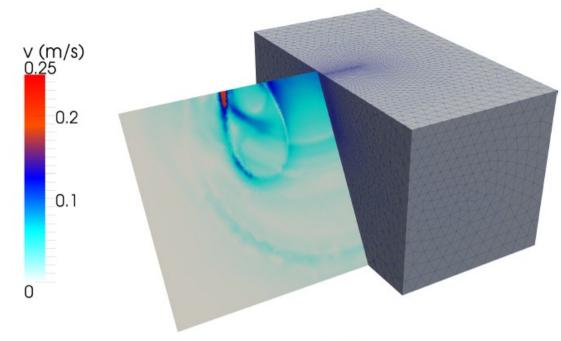
 v_0 steady-state reference velocity μ_0 steady-state reference friction

Dipping fault geometry

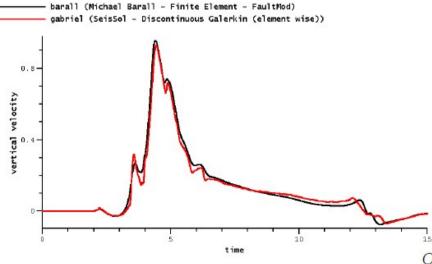
(SCEC Test Cases TPV10 and TPV11)

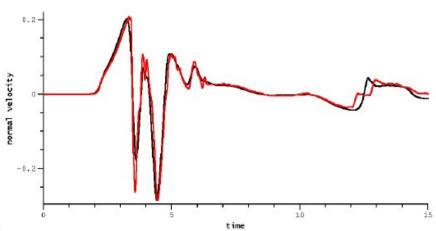
- · 60 degree dipping normal fault geometry
- · Initial stress linearly depth dependent
- Subshear / supershear rupture conditions





Mesh geometry, computational domain and particle velocity on the fault plane after ~9.6 s



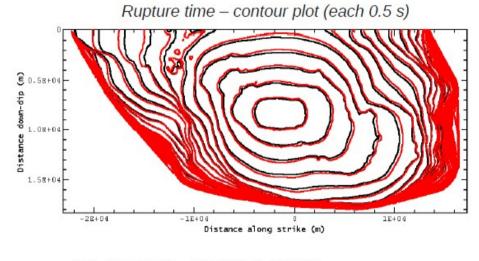


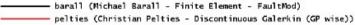
Off- fault station (body 1.0 km, strike 0.0 km, depth 0.0 km)

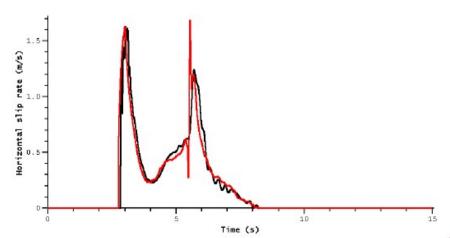
Heterogeneous background stress

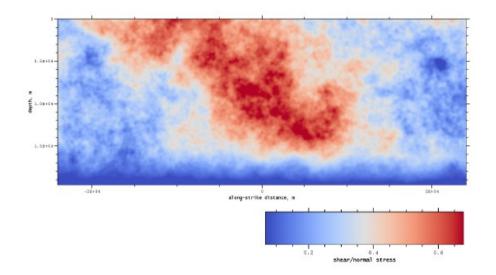
(SCEC Test Cases TPV16 and TPV17)

- · Vertical strike-slip fault
- · Randomly-generated heterogeneous initial stress conditions
- Trilinear interpolation to map background values on irregular distributed integration points

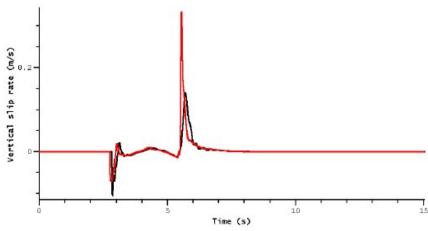








Initial shear stress on the fault plane

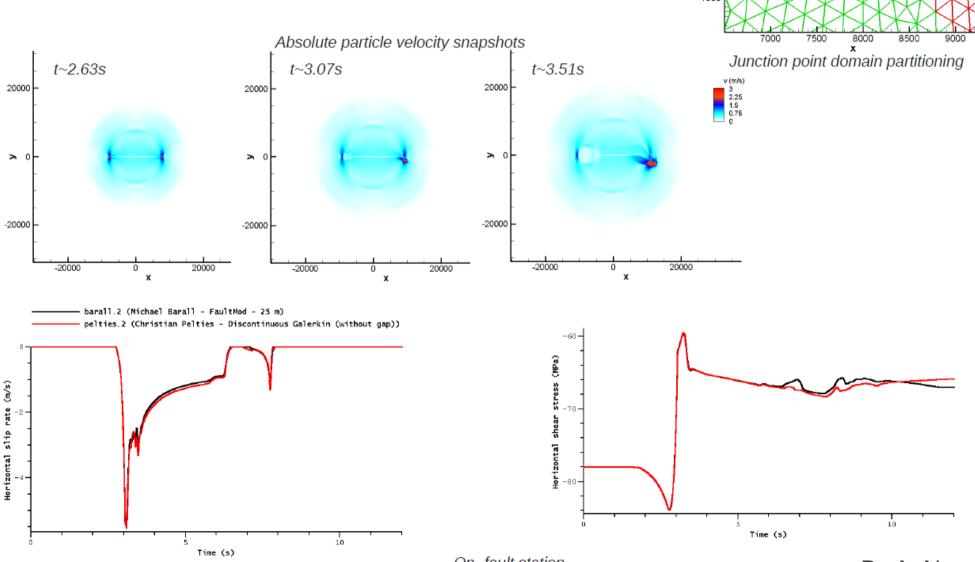


On- fault station (strike -9.0 km, dip 9.0 km)

Fault branching geometry

(2D SCEC Test Cases TPV14 and TPV15)

- Left-lateral, vertical, strike-slip fault with a rightward branch forming a 30 degree angle
- · Slightly stress-heterogeneous
- · High resolution required



500

-500

On- fault station (branch, strike 2.0 km, dip 7.5 km)

By A. Nerger

Tohoku

