

**3D spherical convective dynamo models  
(a history of)**

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## **Approximations**

**Boussinesq or anelastic or fully compressible**

**Explicit or implicit Coriolis terms**

**Lantz-Braginsky-Roberts formulation**

**Solve for pressure**

**Thermal variable: temperature, entropy, enthalpy**

# Numerical methods

## Spectral methods:

**spherical harmonics is latitude and longitude**

**Chebyshev polynomials or finite differences in radius**

**Glatzmaier (solar dynamo) -> *ASH* (Clune, Miesch, Toome, Brun, ...  
(geodynamo) -> *Mag, Magic* (Christensen, Olson, Wicht, ...**

**Kuang, Bloxham, Stanley, ...**

**Dormy, Cardin, Aubert, ...**

**Jones, Boronski, Kuzanyan, Willis, Sarson, Gibson, ...**

**Tilgner, Grote, Busse, ...**

**Sakuraba, Kono, ...**

**Takahashi, Matsushima, Honkura, ...**

**Kida, Kitauchi, ...**

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## Numerical methods

### Local methods:

**Finite difference: Gilman**

**Finite difference: Kageyama**

**Finite difference, Yin-Yang: Kageyama**

**Finite difference, overlapping grids: Wu and Roberts**

**Finite element, cubed sphere: Matsui and Buffett**

**Finite volume, cubed sphere: Harder and Hansen**

**Finite volume: Heyda and Reshetnyak**

**Finite element method: Chan and Zhang**

**Spectral element method: Fischer; Fournier (dynamo?)**

## **Spectral methods**

### **Advantages**

- **high accuracy (as seen in dynamo benchmarks)**
- **avoids the “pole problem”**
- **easily matches magnetic field to external potential field**
- **poloidal / toroidal decomposition => divergence-free fields**

### **Disadvantages**

- **global communication => expensive at high resolution, which will require much greater bandwidth and smaller latency**
- **poor advection near poles**
- **spherical boundaries**
- **grid too fine near center**

**Computational time (dominated by Legendre transforms) and is roughly comparable to communication time (dominated by transposes).**

